### **GEFRAN**

## **PMA12**

# SELF-SUPPORTING LINEAR POSITION TRANSDUCER WITH MAGNETIC PULLING



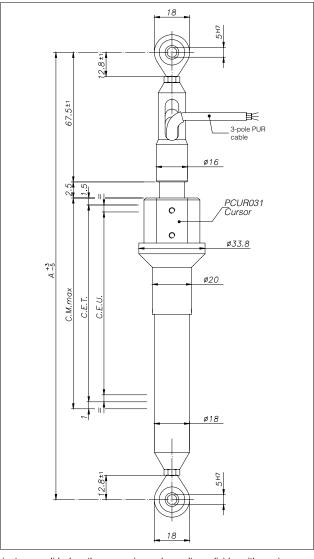
#### Principal characteristics

- The PMA-12 transducer, a development of the PME series, is designed for installation with self-aligning joints.
- The IP67 protection level makes the PMA-12 highly suitable for humid and wet environments and in temporary immersion (CEI EN 60529).
- · Available only with cable output.
- Ideal for applications on metalworking and ceramics machines, as well as on earth-moving machines and utility vehicles. Recommended in all cases where the angle of the drive axle changes constantly.

#### **TECHNICAL DATA**

Useful electical stroke (C.E.U.	50 to 1000mm
Independent linearity	see table
(within C.E.U.)	
Resolution	Infinite
Repeatability	≤ 0,08 mm
Hysteresis	≤ 0,25mm
Electrical connection	PMA12 F 3-pole shielded cable 1m
Protection level	IP67 (CEI EN 60529)
Life	> 25x106 m strokes, or
	> 100x10 <sup>6</sup> operations, whichever
	is less
Displacement speed	≤ 5 m/s
Max. acceleration	≤ 10m/s² displacement
Shock test DIN IEC68T2-27	50g, 11ms single stroke
Vibraziotions DIN IEC68T2-6	12g, 102000Hz
Cursor dragging force	≤ 0.5 N
Displacement sensitivity	da 0.05 a 0.1 mm
(no hysteresis)	
Tracking error	See table
Tolerance on resistance	±20%
Recommended cursor	< 0,1 µA
current	
Maximum cursor current in	
case of bad performances	10mA
·	
Maximum applicable voltage	See table
Electrical isolation	>100MΩ at 500V=, 1bar, 2s
Dielectric strength	< 100µA at 500V~, 50Hz, 2s, 1bar
Dissipation at 40°C	See table
(0W at 120°C)	
Thermal coefficient	-200 +200 ppm/°C typical
of resistance	
Actual Temperature Coefficient	≤ 5 ppm/°C typical
of the output voltage	
Working temperature	-30+100°C
Storage temperature	-50+120°C
Material for transducer	Anodised aluminium, PSU
case	
Material for cursor magnets	POM
Mounting	Self-aligning joints with adjustable
	distance between centres

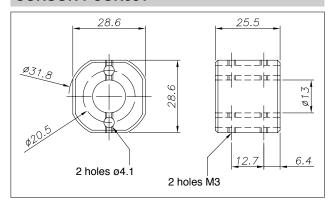
#### **MECHANICAL DIMENSIONS**



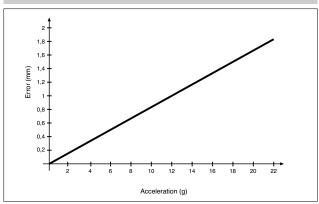
Important: all data shown in the catalog for linearity values and temperature coefficients are valid when the sensor is used as voltage divider with maximum current of Ic•0.1µA in the circuit.

ELECTRICAL / MECHANICAL DATA																							
MODEL		50	100	150	200	250	300	350	400	450	500	550	600	650	700	750	800	850	900	950	1000		
Useful electrical stroke (U.E.S.) + 1 / -0	mm		Model																				
Theoretical electrical stroke (T.E.S.) ± 1	mm		U.E.S. + 1																				
Resistance (on T.E.S.)	kΩ	5							10						20								
Independent linearity (within U.E.S.)	±%	0	,1					0,05															
Dissipation at 40°C (0W at 120°C)	W	1	2	2 3																			
Max. applicable voltage	٧	40	40 60																				
Mechanical stroke MC	mm		U.E.S. + 3,5																				
Case length (A)	mm		U.E.S. + 155																				

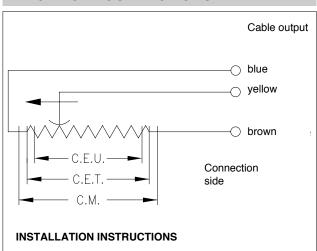
#### **CURSOR PCUR031**



#### **TRACKING ERROR**

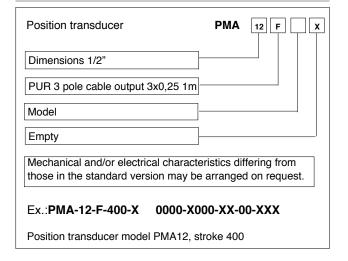


#### **ELECTRICAL CONNECTIONS**

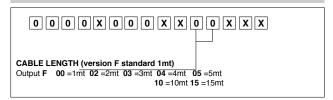


- Respect the indicated electrical connections
  (DO NOT use the transducer as a variable resistance)
- When calibrating the transducer, be careful to set the stroke so that the output does not drop below 1% or rise beyond 99% of the supply voltage.

#### **ORDER CODE**



#### **CODE EXTENSION**



GEFRAN spa reserved the right to make aesthetic or functional changes at any time and without notice.

